## IRB 58 Small

## Compact and accurate



## Compact design

The IRB 58 is a compact six-axes robot with the unique ABB Hollow Wrist. It is based on the standard IRB 580 robot, though using a horizontal arm of 1220 mm, a vertical arm of 700 mm and a narrow base.

It delivers high finish quality and reduced overspray - in a small space.

## **Accurate**

The main benefit of ABB's Hollow Wrist Technology is that all paint and air supply hoses are encapsulated in the arm and wrist. This prevents damage to the hoses, and the straight design eliminates wear and tear thus increasing overall reliability and reducing maintenance.

## **Flexible**

The high precision hollow wrist provides accurate positioning of atomizers. With its unsurpassed working envelope it can rotate +/- 140 degrees in any direction, and enables the robot to cover the most complicated shapes and areas, even at the back of the object.

It is ideal where floor space is limited. It uses state of the art motor, motor drive and transmission technology, giving it high speed and acceleration.

## Global Controller platform

The controller is modular and designed to the highest level of operational reliability.

## Paint application

- Built in triggervalves in the vertical arm
- Process/regulation equipment controlled from the ABB Robot controller
- Painting speed up to 1372 mm/sec

## **Dynamic modelling**

With full dynamic modelling, the IRB 58 robot will always work at optimal acceleration and speed to reduce the cycle time and increase the robot lifetime.

The dynamic model with its enhanced software uses the identified loads to optimize motion performance.



# ROBOTICS, P.O BOX 265, N-4349 BRYNE, NORWAY ABB AS,

## PR10336EN R1

## **TECHNICAL DATA**

## **TECHNICAL MODEL NO: IRB 580-12S**

**SPECIFICATIONS** 

Handling capacity HW 10 kg (500mm COG offset)

Number of axes

Axis movements:

Working range Max. speed Axis 1. Rotation 300° 112%s 2. Vertical arm 145° 112%s 3. Horizontal arm 95° 112%s 4. Inner Wrist indefinite 415%s 5. Wrist Bend indefinite 400 %s 6. Outer Wrist 920° 560 %s

+/- 0,15 mm Pose accuracy Path accuracy 3 mm

## **ELECTRICAL CONNECTION**

3 ph, 200-600 V, 50/60 Hz Supply voltage

Stand by Power consumption <300W During production <700W **Electrical Safety** According to international standards

**PHYSICAL** 

660 X 750 mm Robot Footprint Vertical arm L 700 mm Horizontal arm L 1220 mm

Robot Controller H 1280, W 800, D 550 mm

Total height 1620 mm

Weight:

Robot Unit 542 kg Robot Controller 240 kg

## **ENVIRONMENT**

Explosion protection:

North America Class I&II, Division 1, Group C,D&G, 135 ℃ II 2G,D (T65°C) II B T4 (Zone 1) Japan Europe II 2G,D (T65°C) II B T4 (Zone 1) Electro Magnetic Compatibility certificate FMC Ambient temperature Robot Unit 5-45℃ Robot Controller 5-52℃ Relative humidity Non condensing max. 95% Degree of protection Protection Standards IEC 529

Robot Unit IP 67 Wrist IP 54 Robot Controller IP 54

## **USER INTERFACES**

In cabinet or external Operator panel

EExi protected. Portable, joystick and Programming unit

keyboard

Configurable on screen menus Safety EMY stop, Enable device, General mode

stop, Auto mode stop, Test mode stop, Cabin

interlock

## **MACHINE INTERFACES**

Digital inputs/outputs 512/512 Analog inputs/outputs 16/12

Interbus-S 64/64 Remote I/O

Allen Bradley RIO 128/128 ProfiBus DP 128/128

CC Link

Ethernet NFS/FTP Network

FactoryWare interface

DDE server

Diskette drive 3.5" MS-DOS format

## **ROBOTWARE PAINT**

BaseWare OS Robot Operating System, multitasking

capability.

RAPID Powerful application programming language.

Conveyor Tracking Accurate synchronization of robotic motion,

paint process regulation and the moving part for both linear and circular tracking in any

direction.

IPS Regulation of atomizer, fluid and air. High speed control for paint and air flow

adjustments with the unique ABB Brush

**PC TOOLS** 

A Computer Aided Painting package CAP

containing ShopFloor Editor and RobView.

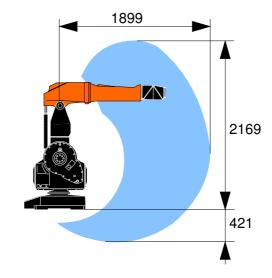
Off-Line editing of programs using 3D ShopFloor Editor graphics for path and process tuning.

Monitoring of robots and process in production. Easy design of user screens.

RobotStudio

RobView

## **WORKING AREA**



Data and dimensions may be changed without notice.

